Towards a Complete Solution to Mobility Management for Multiple-Operability Mobile Systems

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I. INTRODUCTION

The Multiple-Operability Mobile systems are envisioned to integrate many heterogeneous existing systems into a seamless radio infrastructure capable of delivering to mobile users (MUs) a wide range of services (fast Internet access, image processing, videoconferencing) [2-9,12,11-15,14]. Such an infrastructure will implement terminal mobility, personal mobility, and service portability. Terminal mobility refers to the ability to route calls to mobile terminals (MTs) regardless of their point of attachment to the network, while personal mobility is the ability of the MUs to access their personal services independent of their attachment point or terminal. Service portability allows the MUs to move across different network backbones, service providers, and geographical boundaries, and to receive their personalized end-to-end services regardless of their current network. Such a freedom requires the system to interoperate with both wireline and wireless networks, and makes it difficult to locate MUs as they move across various regions and heterogeneous networks. In a mobile network, the service area is partitioned into several location areas (LAs), and each LA covers several cells [13].

Mobile terminals are required to update their location information with the network whenever they enter a new LA. This enables the network to know exactly their residing LA at any time [2]. Implementing LA-based methods for mobility management requires the use of several databases. Generally, a home location register (HLR) database and several visitor location register (VLR) databases are included in the network architecture [13,2]. When a user first subscribes to wireless services, a permanent record of his/her profile is created in the HLR. Since this user may move from one LA to another, his/her current location is usually maintained in a VLR, and must be identified before the setup of any connection.

Mobility management contains two processes: location management and handoff management [3,5,6,9–11].

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Location management is a two-stage process that enables the network to notify the current attachment point of any MT for call delivery. The first stage is location registration (or location update), where the current location of the MT is updated in the appropriate databases (VLR, HLR) [14]. The second stage is call delivery which consists of two major steps: determining the serving VLR of the called MT and locating the visited cell of the called MT. Research in this area generally aims at improving the IS-41 location management scheme while keeping the basic database network unchanged [10,15,2].

Moreover, handoff management is a three-stage process which enables a call in progress to continue as the mobile user (MU) moves between LAs [14]. The first stage involves initiation, where either the user, a network agent, or changing network conditions identify the need for handoff. The second stage refers to generation of a new connection, where the network finds new resources for the handoff connection and performs additional routing operations. The final stage involves data flow control, where data delivery from the old to the new connection path is maintained according to certain quality of service (QoS) requirements.

However, all the schemes presented above only concern intrasystem roaming, i.e. the MUs' movements are limited within LAs of a particular network. This aspect has been comprehensively investigated for stand-alone wireless net-works over the past decade [10,15,2]. Generally, methods for solving such a problem are classified into two categories [2]. The first category includes all the schemes based on algorithms and network architecture. The second category gathers the methods based on learning process, which requires statistics on user mobility behavior. While the first category uses static algorithms, the second uses dynamic methods [15,2]. However, for the NG wireless systems, we consider intersystem or global roaming, which refers to MUs who move between different backbones, protocols, and service providers

This paper presents an approach which can improve the performance of the NG wireless systems, in terms of generated signaling traffic and response time during the global roaming process. It is organized as follows. Section 2 presents background and research related to global mobility management. Section 3 describes the proposed approach for global roaming management. Section 4 defines the main parameters for performance evaluation. Section 5 presents computational results, whereas Section 6 provides some concluding remarks.



Fig. 1. Representation of a three-subsystem heterogeneous network.



Fig. 2. Architecture with an MHLR for global roaming management.

In the NG wireless systems, MUs will be able to pass through various subsystems implementing different technologies and protocols, while being in communication. Each subsystem uses its own registration procedures and the information format stored in the mobility databases (HLRs and VLRs) are different from one subsystem to another. It has been proven in [7] that global roaming increases the network-signaling traffic significantly. In this context, several schemes have been

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recently proposed to reduce such a traffic and maintain good QoS requirements [3,1,4,9,5,2].

Fig. 1 gives an example of a network which consists of three subsystems. This network allows an MU to travel from any subsystem to another. In this case, subsystem 1 may represent the North American Interim Standard 95 (IS-95) system, while subsystem 2 may represent the European Global System for Mobile Telecommunications (GSM) and subsystem 3 a wireless ATM (WATM) network. In this context, intersystem location update concerns updating the location information of an MT performing intersystem roaming, whereas intersystem paging is aimed at searching for the called terminal roaming between different service areas.

As the subsystems use different registration procedures and protocols, it seems difficult to merge HLRs of the individual systems into a single HLR. Thus, a reasonable approach is to build an architecture with a tier manager called Multi-tier HLR (MHLR) which communicates with the heterogeneous HLRs [13,14]. Such an architecture is illustrated in Fig. 2 for a three-subsystem heterogeneous network. With the MHLR, two registration strategies have been proposed: Single Registration (SR) and Multiple Regis-tration (MR) methods [13]. The SR strategy enables the MT to register with the MHLR on only one subsystem at any time to indicate its current location. Ref. [13] illustrates the different registration/deregistration operations executed when an MT moves from subsystem i to subsystem j.As for the MR method, it enables the MT to register with the MHLR on multiple subsystems at any time concurrently, i.e. individual subsystems perform their roaming management as if they are not integrated. Also, Ref. [13] illustrates the operations executed when anMT moves from subsystem i to subsystem j. However, such an architecture may generate a huge amount of signaling traffic at the MHLR, which may impact the QoS expected from the network.

2. THE PROPOSED APPROACH:



Fig. 3. Interconnection of WINGs with HLRs for a three-subsystem network

The proposed approach uses a special gateway called Wireless INterworking Gateway (WING) between each pair of adjacent networks in order to reduce the signaling traffic at the databases (HLRs, VLRs) and interoper-ability between facilitate heterogeneous subsystems in the context of global roaming.More specifically, for each pair of adjoining subsystems i and j, a WING, denoted WINGij, is set up to interconnect directly HLRi to HLRj, while being accessible to both subsystems. Fig. 3 illustrates such an interconnec-tion for a three-subsystem network. The WING contains a number of converter modules which ensure conversion of signaling message formats and perform protocol translation from subsystem i to subsystem j (or vice versa), with respect to syntax and semantics. In particular, different maximum message sizes and different addressing schemes must be converted flexibly.

In this case, the maximum segment size is defined as the largest segment size that the underlying networks can carry without any fragmentation. Also, when transmission speeds of networks differ greatly, rate of transformation has to be processed at the WING, i.e. the converters have the capability to transcode high-speed data into low-speed data. Moreover, a WING supports two types of interfaces: air interface to capture roaming information from any mobile requesting a registration, and a number of serial line interfaces for interconnecting subsystem i with subsystem j. The number of serial line connections depends on the configuration of the adjacent networks the WING inter-connects. Also, the WING has a receiver buffer for registration of signaling request

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messages. As recommended by the UMTS Technical Specifications, the buffer size may be fixed at 8192 bytes [1]. In the same vein, the memory used to store packets awaiting processing or currently processed by the forwarding CPU may be fixed at 16 MB, whereas the maximum rate at which the traffic is switched at the WING is 500,000 packets/s. This guarantees that processed packets remain in that memory until sent out on an appropriate interface, or forwarded to the appropriate slot memory. Hence, a WING is an intelligent switch specially designed for the exchange of information needed between adjacent heterogeneous systems. It possesses the following functionalities: Transforming messages and signaling formats from any network to another, Maintaining the roaming information of MUs after any location registration or update, and being able to retrieve such information at any time, Enabling reliable transmission of call delivery and signaling information (i.e. performing error control), Ensuring mobile users' authentication for secure data delivery.

3.EVALUATION OF QUERY AND UPDATE RATES:

The signaling traffic related to global mobility consists of registration, deregistration, call origination and call delivery. In terms of database activity, such a traffic may be considered as of two kinds: query and update [10]. Evaluation of the query/update rates is based on the mobility model which describes the MU movements, taking into account the speed, direction, and movement history of each MU. Ref. [11] gives a description of several mobility models. However, in the context of this research, we consider a variation of the Fluid Flow Model to characterize movement behavior. According to this model, MUs in subsystem i are assumed to move at an average speed of vi, while having a direction of movement uniformly distributed over [0,2p]. Assuming that these MUs are uniformly distributed throughout subsystem i with a density ri, and the boundary of subsystem i is of length Li, the rate of users moving out of subsystem i to subsystem j is given by: $r_{ij} = Zi vi L i / \prod$ (1)

4. RESULTS:

TABLE 1: PARAMETERS FOR GLOBAL ROAMING ANALYSIS

Parameter	Subsystem i	Subsystem j
Number of LAs	6	4
Cell area (km ²)	0.04	36.0
Average speed (km/h)	5.0	20.0
Number of VLRs	6	4
Number of HLR	1	1
λin (calls/second/	8.333×10 ⁻⁴	5.556×10 ⁻⁵
λ _{out} (calls/second/ terminal)	5.556×10 ⁻⁴	2.7778×10 ⁻⁴



Fig. 4. Impact of user behavior on query rate.



Fig. 5. Impact of user behavior on update rate.

5. CONCLUSION:

This paper has presented an efficient approach to facilitate interoperability between different subsystems of the NG wireless networks. Numerical results reveal that such an approach significantly improves the results obtained from SR, MR and WING methods, in terms of generated signaling traffic and response time during the global roaming process. From the result analysis, we may deduce the following advantages of the proposed approach: low query/update rates at the database level, rapid user location, simple implementation, and low response time.

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